2. Matrix Algebra

A linear system of m equations in n unknowns,

$$a_{11}x_{1} + a_{12}x_{2} + \dots + a_{1n}x_{n} = b_{1}$$

$$a_{21}x_{1} + a_{22}x_{2} + \dots + a_{2n}x_{n} = b_{2}$$

$$\vdots$$

$$a_{m1}x_{1} + a_{m2}x_{2} + \dots + a_{mn}x_{n} = b_{m}$$

(where the a_{ii} and b_i are constants)

can be written more concisely in matrix form, as

$$A \vec{\mathbf{x}} = \vec{\mathbf{b}}$$

where the $(m \times n)$ coefficient matrix [m rows and n columns] is

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

and the column vectors (also $(n \times 1)$ and $(m \times 1)$ matrices respectively) are

x =	$\begin{array}{c} x_1 \\ x_2 \\ \vdots \end{array}$	and $\mathbf{\bar{b}} =$	$\begin{bmatrix} b_1 \\ b_2 \\ \vdots \end{bmatrix}$
	<i>x</i> _{<i>n</i>}		b_m

Matrix operations can render the solution of a linear system much more efficient.

Sections in this Chapter

- 2.01 Gaussian Elimination
- 2.02 Summary of Matrix Algebra
- 2.03 Determinants and Inverse Matrices
- 2.04 Eigenvalues and Eigenvectors

2.01 Gaussian Elimination

Example 2.01.1

In quantum mechanics, the Planck length L_P is defined in terms of three fundamental constants:

- the universal constant of gravitation,	$G = 6.67 \times 10^{-11} \text{ N m}^2 \text{ kg}^{-2}$
- Planck's constant,	$h = 6.62 \times 10^{-34} \text{ J s}$
- the speed of light in a vacuum,	$c = 2.998 \times 10^8 \text{ m s}^{-1}$
The Planck length is therefore	

$$L_P = k G^x h^y c^z$$

where k is a dimensionless constant and x, y, z are constants to be determined. Also note that $1 \text{ N} = 1 \text{ kg m s}^{-2}$ and $1 \text{ J} = 1 \text{ Nm} = 1 \text{ kg m}^2 \text{ s}^{-2}$. Use dimensional analysis to find the values of x, y and z.

Let
$$\begin{bmatrix} L_P \end{bmatrix}$$
 denote the dimensions of L_P .
Then $\begin{bmatrix} L_P \end{bmatrix} = \begin{bmatrix} k G^x h^y c^z \end{bmatrix} = \begin{bmatrix} G \end{bmatrix}^x \begin{bmatrix} h \end{bmatrix}^y \begin{bmatrix} c \end{bmatrix}^z = (kg^{-1}m^3s^{-2})^x (kg m^2s^{-1})^y (m s^{-1})^z$
 $= kg^{-x+y}m^{3x+2y+z}s^{-2x-y-z} = \begin{bmatrix} L_P \end{bmatrix} = m^1$

This generates a linear system of three simultaneous equations for the three unknowns,

kg:
$$-x + y = 0$$

m: $3x + 2y + z = 1$
s: $-2x - y - z = 0$

This can be re-written as the matrix equation $A\mathbf{x} = \mathbf{b}$, where

$$\mathbf{A} = \begin{bmatrix} -1 & 1 & 0 \\ 3 & 2 & 1 \\ -2 & -1 & -1 \end{bmatrix}, \quad \mathbf{\bar{x}} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad \mathbf{\bar{b}} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Use Gaussian elimination (a sequence of row operations) on the augmented matrix [A | b] :

$$\begin{bmatrix} \mathbf{A} | \vec{\mathbf{b}} \end{bmatrix} = \begin{bmatrix} -1 & 1 & 0 & 0 \\ 3 & 2 & 1 & 1 \\ -2 & -1 & -1 & 0 \end{bmatrix}$$

Multiply Row 1 by (-1):

$$\xrightarrow{R_1 \times -1} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 3 & 2 & 1 & 1 \\ -2 & -1 & -1 & 0 \end{bmatrix}$$

There is now a "leading one" in the top left corner.

Example 2.01.1 (continued)

From Row 2 subtract $(3 \times Row 1)$ and to Row 3 add $(2 \times Row 1)$:

$$\xrightarrow[R_2 - 3R_1]{R_3 + 2R_1} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 5 & 1 & 1 \\ 0 & -3 & -1 & 0 \end{bmatrix}$$

All entries below the first leading one are now zero. The next leading entry is a '5'. Scale it down to a '1'. Multiply Row 2 by (1/5):

$$\xrightarrow[R_2 \times \frac{1}{5}]{} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & \boxed{1} & \frac{1}{5} & \frac{1}{5} \\ 0 & -3 & -1 & 0 \end{bmatrix}$$

Clear the entry below the new leading one. To Row 3 add $(3 \times Row 2)$:

$$\xrightarrow{R_3 + 3R_2} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & \frac{1}{5} & \frac{1}{5} \\ 0 & 0 & -\frac{2}{5} & \frac{3}{5} \end{bmatrix}$$

The next leading entry is a '-2/5'. Scale it down to a '1'. Multiply Row 3 by (-5/2):

$$\xrightarrow{R_3 \times -\frac{5}{2}} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & \frac{1}{5} & \frac{1}{5} \\ 0 & 0 & 1 & -\frac{3}{2} \end{bmatrix}$$

This matrix is in **row echelon form** (the first non-zero entry in every row is a one and all entries below every leading one in its column are zero). It is also **upper triangular** (all entries below the leading diagonal are zero).

The solution may be read from the echelon form, using back substitution:

$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & \frac{1}{5} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{1}{5} \\ -\frac{3}{2} \end{bmatrix} \implies z = -\frac{3}{2} \implies y + \frac{1}{5} \times \left(-\frac{3}{2}\right) = \frac{1}{5} \implies y = \frac{1}{5} \times \frac{5}{2} = \frac{1}{2}$$
$$\implies x - \frac{1}{2} = 0 \implies x = \frac{1}{2}$$

Example 2.01.1 (continued)

An alternative strategy is to complete the reduction of the augmented matrix to **reduced row echelon form** (the first non-zero entry in every row is a one and all other entries are zero in a column that contains a leading one).

From Row 2 subtract $(1/5 \times \text{Row 3})$:

$$\xrightarrow{R_2 - \frac{1}{5}R_3} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & -\frac{3}{2} \end{bmatrix}$$

To Row 1 add Row 2:

$$\xrightarrow{R_1 + R_2} \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{2} \\ 0 & 1 & 0 & | & \frac{1}{2} \\ 0 & 0 & 1 & | & -\frac{3}{2} \end{bmatrix}$$

From this reduced row echelon matrix, the values of x, y and z may be read directly:

	[1	0	0	$\begin{bmatrix} x \end{bmatrix}$		$\frac{1}{2}$			
\rightarrow	0	1	0	y	=	$\frac{1}{2}$	>	$x = y = \frac{1}{2},$	$z = -\frac{3}{2}$
	0	0	1			$\left[-\frac{3}{2} \right]$			

When a square linear system (same number of equations as unknowns) has a unique solution, the reduced row echelon form of the coefficient matrix is the identity matrix.

Therefore the functional form of the Planck length is

$$L_P = k \sqrt{\frac{Gh}{c^3}} = \frac{k}{c} \sqrt{\frac{Gh}{c}}$$

Dimensional analysis alone cannot determine the value of the constant *k*.

[Methods in quantum mechanics, beyond the scope of this course, can establish that the

constant is $k = \frac{1}{2\pi}$, so that $L_P = 1.61620 \times 10^{-35}$ m.]

Example 2.01.2

Find the solution (x, y, z, t) to the system of equations

x + y = 5 y + z = 72y + z + t = 10

This is an **under-determined system** of equations (fewer equations than unknowns). A unique solution is not possible. There will be either infinitely many solutions or no solution at all.

Reduce the augmented matrix to reduced row echelon form:

A leading one exists in the top left entry, with zero elsewhere in the first column. A leading one exists in the second row. Clear the other entries in the second column. From Row 3 subtract $(2 \times Row 2)$ and from Row 1 subtract Row 2:

$$\xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & -1 & 0 & | & -2 \\ 0 & \boxed{1} & 1 & 0 & | & 7 \\ 0 & 0 & -1 & 1 & | & -4 \end{bmatrix}$$

Rescale the leading entry in Row 3 to a '1'. Multiply row 3 by (-1):

	1	0	-1	0	-2
$\xrightarrow{R \times -1}$	0	1	1	0	7
$\kappa_3 \wedge 1$	0	0	1	-1	4

Clear the other entries in the third column. From Row 2 subtract Row 3 and to Row 1 add Row 3:

	1	0	0	-1	2
$\xrightarrow{R_1 + R_3} \xrightarrow{R_1 - R}$	0	1	0	1	3
$\kappa_2 - \kappa_3$	0	0	1	-1	4

The leading ones are identified in this row reduced echelon form.

Example 2.01.2 (continued)

$$\begin{bmatrix} \boxed{1} & 0 & 0 & -1 \\ 0 & \boxed{1} & 0 & 1 \\ 0 & 0 & \boxed{1} & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

The fourth column lacks a leading one. This means that the fourth variable, t, is a free parameter, in terms of which the other three variables may be expressed. We therefore have a **one-parameter family of solutions**,

x-t=2, y+t=3, z-t=4

 \Rightarrow or

(x, y, z, t) = (2, 3, 4, 0) + (1, -1, 1, 1) twhere t is free to be any real number.

x = 2 + t, y = 3 - t, z = 4 + t

The **rank** of a matrix is the number of leading ones in its echelon form.

If rank (A) < rank [A | b], then the linear system is **inconsistent** and has no solution.

If rank (A) = rank $[A | \mathbf{b}] = n$ (the number of columns in A), then the system has a unique solution for any such vector \mathbf{b} .

If rank (A) = rank $[A | \mathbf{b}] < n$, then the system has infinitely many solutions, with a number of parameters = $(n - \operatorname{rank}(A)) = (\# \operatorname{columns in} A_r \text{ with no leading one}).$

Example 2.01.3

Read the solution set $(x_1, x_2, ..., x_n)$ from the following reduced echelon forms. (a)

 $\begin{bmatrix} \boxed{1} & 0 & -2 & 1 & | & 1 \\ 0 & \boxed{1} & 1 & 0 & | & 2 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$ rank (A) = rank [A | **b**] = 2, n = 4

Two-parameter family of solutions:

 $(x_1, x_2, x_3, x_4) = (1, 2, 0, 0) + (2, -1, 1, 0) x_3 + (-1, 0, 0, 1) x_4$

Example 2.01.3

(b)					
1	0	-2	1	1	
0	1	1	0	2	$\operatorname{rank}(A) < \operatorname{rank}[A \mathbf{b}] \implies \operatorname{no solution}$
0	0	0	0	1	

(c)

$$\begin{bmatrix} 1 & 0 & 0 & a \\ 0 & 1 & 0 & b \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

rank (A) = rank [A | **b**] = $n = 3 \implies$ unique solution

This is an **over-determined system** of five equations in three unknowns, but two of the five equations are superfluous and can be expressed in terms of the other three equations. In this case a unique solution exists regardless of the values of the numbers a, b, c.

The solution is

$$(x_1, x_2, x_3) = (a, b, c)$$

Note that software exists to eliminate the tedious arithmetic of the row operations. Various procedures exist in Maple and Matlab.

A custom program, available on the course web site at

"www.engr.mun.ca/~ggeorge/9420/demos/", allows the user to enter the coefficients of a linear system as rational numbers, allows the user to perform row operations (but will *not* suggest the appropriate operation to use) and carries out the arithmetic of the chosen row operation automatically.