Interface ADC and Sensors to a PC

• AD558 is configured as “write only”
• VCC range +4.5V ~ +16.5 V, normally +5V
• Vout Range: 0 ~ 2.56 V, or 0 ~ 10 V
• Digital Input Code

<table>
<thead>
<tr>
<th>Binary</th>
<th>Hex</th>
<th>Decimal</th>
<th>2.56V</th>
<th>0.010V</th>
<th>0.150V</th>
<th>2.55V</th>
</tr>
</thead>
<tbody>
<tr>
<td>00000000</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0.000V</td>
<td>0.000V</td>
</tr>
<tr>
<td>00000001</td>
<td>01</td>
<td>1</td>
<td>0.010V</td>
<td>0.039V</td>
<td>0.000V</td>
<td>0.000V</td>
</tr>
<tr>
<td>00001111</td>
<td>0F</td>
<td>15</td>
<td>0.150V</td>
<td>0.586V</td>
<td>0.000V</td>
<td>0.000V</td>
</tr>
<tr>
<td>11111111</td>
<td>FF</td>
<td>255</td>
<td>2.55V</td>
<td>9.961V</td>
<td>0.000V</td>
<td>0.000V</td>
</tr>
</tbody>
</table>

Pin Description

• RD: active low input signal
  – RD is used to get the converted data out of the chip
  – When CS = 0, if a high-to-low pulse is applied to the RD pin, the 8-bit digital output shows up at the D0 – D7 data pins
  – Thus, RD is also referred to as output enable
• WR: active low input signal ⇒ Start Conversion
  – If CS = 0, when WR makes a low-to-high transition, the ADC 804 starts converting the analog input value to an 8-bit digit number
Data Conversion Procedure

- Steps for data conversion by the AD804 chip
  - Make CS = 0 and send a low-to-high pulse to the WR pin to start the conversion
  - Keep monitoring the INTR pin. If INTR is low, the conversion is finished and we can go to the next step. If the INTR is high, keep polling until it goes low
  - After INTR become low, we make CS = 0 and send a high-to-low pulse to the RD pin to get the data out of the AD804 chip
- Example1: AD804, Example2: AD7574

Decoding Methods

- Use 74LS138 Decoder
  - This is one of the most widely used address decoders
  - The 3 pins A, B, C generate 8 active low output Y0 ~ Y7
  - Each Yx output is connected to CS of a memory chip, allowing control of 8 memory blocks by a single decoder
  - In 74LS138, there are additional inputs, G2A, G2B, and G1. G2A and G2B are both active low, and G1 is active high. If any one of the inputs G2A, G2B, and G1 is not connected to an address signal, they must be activated permanently either by Vcc or Gnd.
  - Example: give the range for the memory chip

Methods of Address Decoding

- The CPU provides the address of the data desired, it is the job of the decoding circuitry to locate the data
- In connecting a memory chip to the CPU
  - The data bus is connected directly to memory data pins
  - Control signals MEMR and MEMW are connected to the RD and WR pins of the memory chip
  - For address busses, the lower bits of the address go directly to the memory chip address pins, the upper ones are used to activate the CS pin of the memory chip.
  - No data can be written into or read from the memory chip unless the CS is activated. CS is normally active low.

Decoding Methods

- Simple logical gate as address decoder
  - Use NAND or other gates because the output of NAND gate is active low and that is CS is also active low
  - In the case that the CS input is active high, and AND gate must be used
  - Using a combination of NAND and inverters, one can decode any address range
  - For example: What’s the memory chip address range?