

Input and Output

Dividing behaviours into inputs and outputs

In this course we follow the convention that

- Names of inputs have no primes: x, y, z
- Names of outputs end with a prime: x', y', z'

Given a signature, e.g.:

$$\Sigma = \{“w” \mapsto A, “x” \mapsto B, “y'” \mapsto C, “z'” \mapsto D\}$$

its **input aspect** consists only of inputs

$$\overleftarrow{\Sigma} = \{“w” \mapsto A, “x” \mapsto B\}$$

and its **output aspect** consists only of outputs

$$\overrightarrow{\Sigma} = \{“y'” \mapsto C, “z'” \mapsto D\}$$

Note: No primes

Similarly for behaviours: if

$$b = \{“w” \mapsto m, “x” \mapsto n, “y'” \mapsto p, “z'” \mapsto q\}$$

then

$$\overleftarrow{b} = \{“w” \mapsto m, “x” \mapsto n\}$$

$$\overrightarrow{b} = \{“y'” \mapsto p, “z'” \mapsto q\}$$

Note: The input and output aspects of the signature are rather like the source and target of a relation

We can put together signatures and behaviours using the \dagger operator

$$\{“w” \mapsto A, “x” \mapsto B\} \dagger \{“y'” \mapsto C, “z'” \mapsto D\} = \Sigma$$

$$\{“w” \mapsto m, “x” \mapsto n\} \dagger \{“y'” \mapsto p, “z'” \mapsto q\} = b$$

Response Set

For any particular input, $i : \overleftarrow{\Sigma}$, which outputs are acceptable? Define the **response set** of f_{Σ} for input i as

$$\text{resp}(f_{\Sigma}, i) \triangleq \left\{ o : \overrightarrow{\Sigma} \mid f(i \dagger o) \right\}$$

Note that

$$f \sqsubseteq g \text{ iff } \forall i : \overleftarrow{\Sigma} \cdot \text{resp}(f, i) \supseteq \text{resp}(g, i)$$

So the direction of the \sqsubseteq symbol might seem a little confusing at first.

The size of the response set is worth noting

- f_{Σ} is **determined**, for input i , iff $|\text{resp}(f_{\Sigma}, i)| = 1$.
- f_{Σ} is **underdetermined**, for input i , iff $|\text{resp}(f_{\Sigma}, i)| > 1$.
- f_{Σ} is **overdetermined**, for input i , iff $|\text{resp}(f_{\Sigma}, i)| = 0$.

Nondeterminism

A specification is **deterministic** if it is determined for every input

$$\forall i : \overleftarrow{\Sigma} \cdot |\text{resp}(f_{\Sigma}, i)| = 1$$

If a specification is not deterministic, it is **nondeterministic**

$$\exists i : \overleftarrow{\Sigma} \cdot |\text{resp}(f_{\Sigma}, i)| \neq 1$$

Deterministic specifications are essentially total functions from an input space to an output space

We are interested in nondeterministic specifications because

- They allow us to not specify aspects that are not

important.

- They allow us to model components that are not perfectly reliable.
- They allow us to omit quantities from the system boundary.
- They allow us to freely combine specifications with operators such as 'and' and 'or'.

Implementability

While being underdetermined for one or more inputs is not a problem, there is a problem with specifications that are overdetermined for some inputs.

Such specifications are called **unimplementable**

$$\exists i : \overleftarrow{\Sigma} \cdot \text{resp}(f_{\Sigma}, i) = \emptyset$$

Equivalently

$$\exists i : \overleftarrow{\Sigma} \cdot \forall o : \overrightarrow{\Sigma} \cdot \neg f(i \dagger o)$$

A specification that is not unimplementable is **implementable**

$$\forall i : \overleftarrow{\Sigma} \cdot \text{resp}(f_{\Sigma}, i) \neq \emptyset$$

Equivalently:

$$\forall i : \overleftarrow{\Sigma} \cdot \exists o : \overrightarrow{\Sigma} \cdot f(i \dagger o)$$

The job of a system that meets a requirements specification f is to, for each input, i , select an output o from $\text{resp}(f, i)$.

No physical system can select a behaviour from an empty set.

So no physical system will meet an unimplementable specification.

Example:

$$f = \langle |\sin(x) - x'| < 0.001 \wedge x' \geq 0 \rangle$$

This specification requires that the output is approximately the sine of the input, but also that it not be negative. This is a contradictory specification. For example for $x = \frac{-\pi}{4}$ there is no suitable value for x' .

Commandment: Thou shalt not write unimplementable requirements specifications.