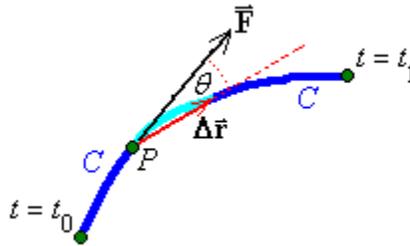


## 8. Line Integrals

Two applications of line integrals are treated here: the evaluation of work done on a particle as it travels along a curve in the presence of a [vector field] force; and the evaluation of the location of the centre of mass of a wire.

### Work done:

The work done by a force  $\vec{F}$  in moving an elementary distance  $\Delta\vec{r}$  along a curve  $C$  is approximately the product of the component of the force in the direction of  $\Delta\vec{r}$  and the distance  $|\Delta\vec{r}|$  travelled:



Integrating along the curve  $C$  yields the total work done by the force  $\vec{F}$  in moving along the curve  $C$ :

$$W = \int_C \vec{F} \cdot d\vec{r}$$

Example 8.01

Find the work done by  $\vec{\mathbf{F}} = [-y \ x \ z]^T$  in moving once around the closed curve  $C$  (defined in parametric form by  $x = \cos t$ ,  $y = \sin t$ ,  $z = 0$ ,  $0 \leq t < 2\pi$ ).

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Example 8.01 (continued)

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Example 8.02

Find the work done by  $\vec{\mathbf{F}} = [x \ y \ z]^T$  in moving around the curve  $C$  (defined in parametric form by  $x = \cos t$ ,  $y = \sin t$ ,  $z = 0$ ,  $0 \leq t < 2\pi$ ).

---

If the initial and terminal points of a curve  $C$  are identical and the curve meets itself nowhere else, then the curve is said to be a **simple closed curve**.

Notation:

When  $C$  is a simple closed curve, write  $\int_C \vec{F} \cdot d\vec{r}$  as  $\oint_C \vec{F} \cdot d\vec{r}$ .

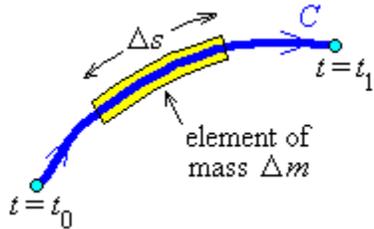
$\vec{F}$  is a **conservative vector field** if and only if  $\oint_C \vec{F} \cdot d\vec{r} = 0$  for all simple closed curves  $C$  in the domain.

Be careful of where the endpoints are and of the order in which they appear (the orientation of the curve). The identity  $\int_{t_0}^{t_1} \vec{F} \cdot \frac{d\vec{r}}{dt} dt \equiv - \int_{t_1}^{t_0} \vec{F} \cdot \frac{d\vec{r}}{dt} dt$  leads to the result

$$\oint_C \vec{F} \cdot d\vec{r} = - \oint_C \vec{F} \cdot d\vec{r} \quad \forall \text{ simple closed curves } C$$

Another Application of Line Integrals: **The Mass of a Wire**

Let  $C$  be a segment ( $t_0 \leq t \leq t_1$ ) of wire of line density  $\rho(x, y, z)$ . Then



First moments about the coordinate planes:

The location  $\langle \vec{r} \rangle$  of the centre of mass of the wire is  $\langle \vec{r} \rangle = \frac{\vec{M}}{m}$ , where the moment

$$\vec{M} = \int_{t_0}^{t_1} \rho \vec{r} \frac{ds}{dt} dt, \quad m = \int_{t_0}^{t_1} \rho \frac{ds}{dt} dt \quad \text{and} \quad \frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right| = \sqrt{\left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2 + \left( \frac{dz}{dt} \right)^2}.$$

Example 8.03

Find the mass and centre of mass of a wire  $C$  (described in parametric form by  $x = \cos t$ ,  $y = \sin t$ ,  $z = t$ ,  $-\pi \leq t \leq \pi$ ) of line density  $\rho = z^2$ .

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Example 8.03 (continued)

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## Green's Theorem

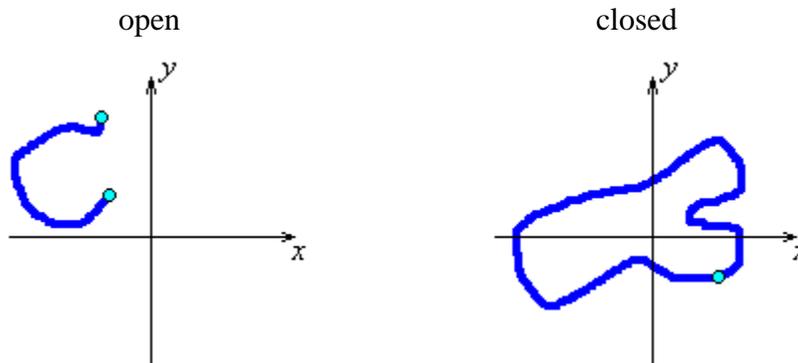
Some definitions:

A curve  $C$  on  $\mathbb{R}^2$  (defined in parametric form by  $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$ ,  $a \leq t \leq b$ ) is **closed** iff  $(x(a), y(a)) = (x(b), y(b))$ .

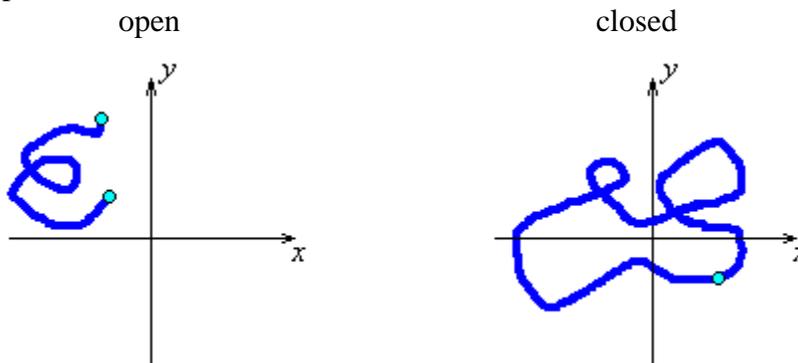
The curve is **simple** iff  $\vec{r}(t_1) \neq \vec{r}(t_2)$  for all  $t_1, t_2$  such that  $a < t_1 < t_2 < b$ ;  
(that is, the curve neither touches nor intersects itself, except possibly at the end points).

### Example 8.04

Two simple curves:



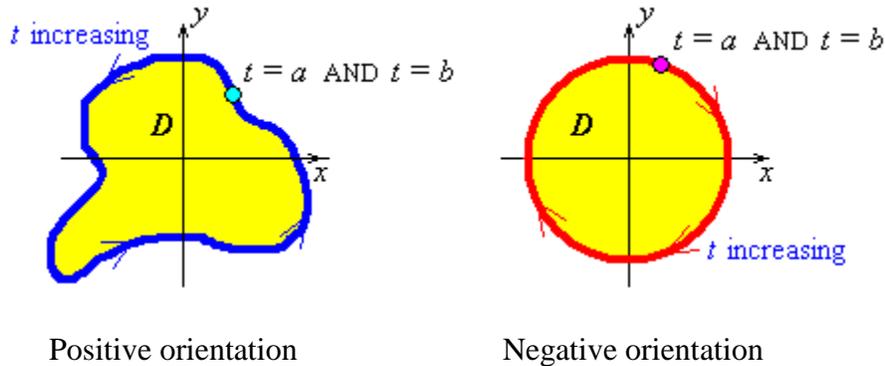
Two non-simple curves:



### **Orientation of closed curves:**

A closed curve  $C$  has a positive orientation iff a point  $\vec{r}(t)$  moves around  $C$  in an anticlockwise sense as the value of the parameter  $t$  increases.

## Example 8.05



Let  $D$  be the finite region of  $\mathbb{R}^2$  bounded by  $C$ . When a particle moves along a curve with positive orientation,  $D$  is always to the left of the particle.

For a simple closed curve  $C$  enclosing a finite region  $D$  of  $\mathbb{R}^2$  and for any vector function  $\vec{\mathbf{F}} = [f_1 \ f_2]^T$  that is differentiable everywhere on  $C$  and everywhere in  $D$ ,

**Green's theorem** is valid:

$$\oint_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \iint_D \left( \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right) dA$$

The region  $D$  is entirely in the  $xy$ -plane, so that the unit normal vector everywhere on  $D$  is  $\hat{\mathbf{k}}$ . Let the differential vector  $d\vec{\mathbf{A}} = dA \hat{\mathbf{k}}$ , then Green's theorem can also be written as

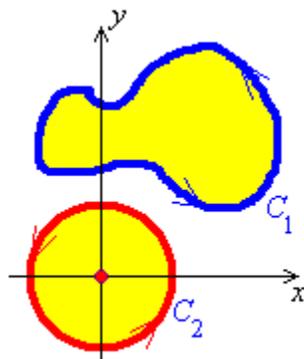
$$\oint_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \iint_D (\vec{\nabla} \times \vec{\mathbf{F}}) \cdot \hat{\mathbf{k}} dA = \iint_D (\text{curl } \vec{\mathbf{F}}) \cdot d\vec{\mathbf{A}}$$

Green's theorem is valid if there are no singularities in  $D$ .

A [non-examinable] proof is provided at the end of this chapter.

Example 8.06

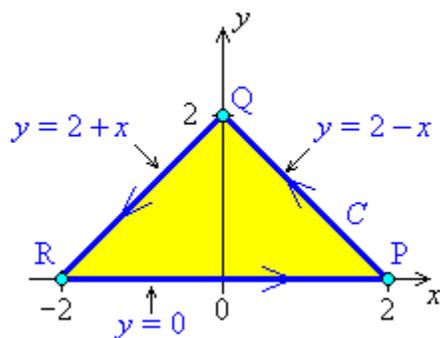
$$\vec{\mathbf{F}} = \begin{bmatrix} x \\ \frac{x}{r} \ 0 \end{bmatrix}^T :$$



---

Example 8.07

For  $\vec{\mathbf{F}} = \begin{bmatrix} x+y \\ x-y \end{bmatrix}$  and  $C$  as shown, evaluate  $\oint_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}}$ .



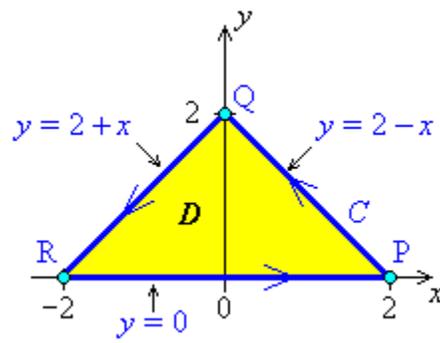
Example 8.07 (continued)

$$\bar{\mathbf{F}} = \begin{bmatrix} x + y \\ x - y \end{bmatrix}$$

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Example 8.07 (continued)

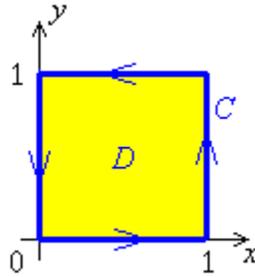
**OR** use Green's theorem!



Example 8.08

Find the work done by the force  $\vec{F} = xy\hat{i} + y^2\hat{j}$  in one circuit of the unit square.

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**Path Independence****Gradient Vector Fields:**

$$\text{If } \vec{\mathbf{F}} = \vec{\nabla}V, \text{ then } \vec{\mathbf{F}} = \left[ \frac{\partial V}{\partial x} \quad \frac{\partial V}{\partial y} \right]^T \Rightarrow$$

---

**Path Independence**

If  $\vec{\mathbf{F}} = \vec{\nabla}V$  (or  $\vec{\mathbf{F}} = -\vec{\nabla}V$ ), then  $V$  is a **potential function** for  $\vec{\mathbf{F}}$ .

Let the path  $C$  travel from point  $P_0$  to point  $P_1$ :

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**Domain**

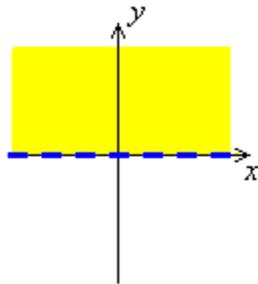
A region  $\Omega$  of  $\mathbb{R}^2$  is a **domain** if and only if

- 1) For all points  $P_0$  in  $\Omega$ , there exists a circle, centre  $P_0$ , all of whose interior points are inside  $\Omega$ ; and
- 2) For all points  $P_0$  and  $P_1$  in  $\Omega$ , there exists a piecewise smooth curve  $C$ , entirely in  $\Omega$ , from  $P_0$  to  $P_1$ .

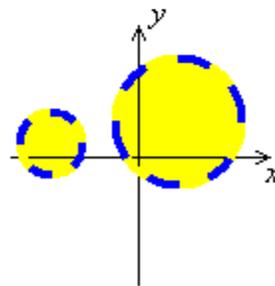
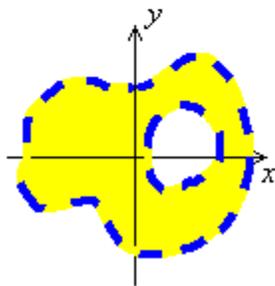
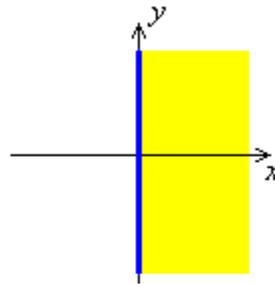
Example 8.09

Are these domains?

$$\{ (x, y) \mid y > 0 \}$$



$$\{ (x, y) \mid x \geq 0 \}$$



If a domain is not specified, then, by default, it is assumed to be all of  $\mathbb{R}^2$ .

When a vector field  $\vec{\mathbf{F}}$  is defined on a simply connected domain  $\Omega$ , these statements are all equivalent (that is, **all** of them are true or all of them are false):

- $\vec{\mathbf{F}} = \vec{\nabla}V$  for some scalar field  $V$  that is differentiable everywhere in  $\Omega$ ;
- $\vec{\mathbf{F}}$  is conservative;
- $\int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}}$  is path-independent (has the same value no matter which path within  $\Omega$  is chosen between the two endpoints, for any two endpoints in  $\Omega$ );
- $\int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = V_{\text{end}} - V_{\text{start}}$  (for any two endpoints in  $\Omega$ );
- $\oint_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = 0$  for all closed curves  $C$  lying entirely in  $\Omega$ ;
- $\frac{\partial f_2}{\partial x} = \frac{\partial f_1}{\partial y}$  everywhere in  $\Omega$ ; and
- $\vec{\nabla} \times \vec{\mathbf{F}} = \vec{\mathbf{0}}$  everywhere in  $\Omega$  (so that the vector field  $\vec{\mathbf{F}}$  is irrotational).

There must be no singularities anywhere in the domain  $\Omega$  in order for the above set of equivalencies to be valid.

#### Example 8.10

Evaluate  $\int_C ((2x + y) dx + (x + 3y^2) dy)$  where  $C$  is any piecewise-smooth curve from  $(0, 0)$  to  $(1, 2)$ .

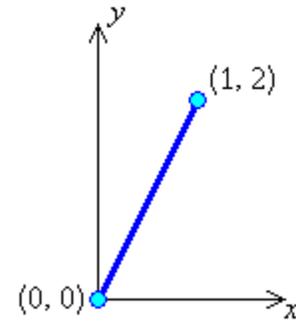
Example 8.10 by direct evaluation of the line integral

Let us pursue instead a particular path from  $(0, 0)$  to  $(1, 2)$ .

The straight line path  $C_1$  is a segment of the line

$$y = 2x \Rightarrow x = \frac{1}{2}y.$$

$$\Rightarrow I = \int_{C_1} \left( (2x + y) dx + (x + 3y^2) dy \right) =$$



An alternative evaluation of  $I = \int_{C_1} \vec{F} \cdot d\vec{r}$  is to use  $x$  as the parameter in both integrals

(that is, to express  $y$  in terms of  $x$  throughout). Then

$$\Rightarrow I = \int_{C_1} \left( (2x + y) dx + (x + 3y^2) dy \right) =$$

An alternative path  $C_2$  involves going round the other two sides of the triangle, first from  $(0, 0)$  horizontally to  $(1, 0)$  then from there vertically to  $(1, 2)$ .

On the first leg  $y \equiv 0 \Rightarrow dy \equiv 0$ ,

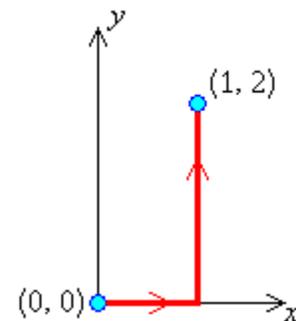
so that the second part of the integral vanishes.

On the second leg  $x \equiv 1 \Rightarrow dx \equiv 0$ ,

so that the first part of the integral vanishes.

Therefore

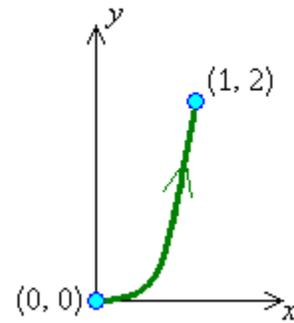
$$I = \int_{C_2} \left( (2x + y) dx + (x + 3y^2) dy \right) =$$



Example 8.10 by direct evaluation of the line integral

Yet another possibility is  $C_3$  an arc of the parabola  $y = 2x^2$ .

$$\Rightarrow I = \int_{C_3} ((2x + y) dx + (x + 3y^2) dy) =$$



---

Note that the above suggests that  $I = \int_{(0,0)}^{(1,2)} \vec{F} \cdot d\vec{r}$  might be path-independent, because evaluations along three different paths have all produced the same answer. But this is *not* a proof of path independence. For a proof, one must establish that  $\vec{F}$  is conservative, either by finding the potential function, or by showing that  $\text{curl } \vec{F} \equiv \vec{0}$ .

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**Outline of a Proof of Green's Theorem** [not examinable]

Let  $\vec{F} = P(x, y)\hat{i} + Q(x, y)\hat{j}$ .

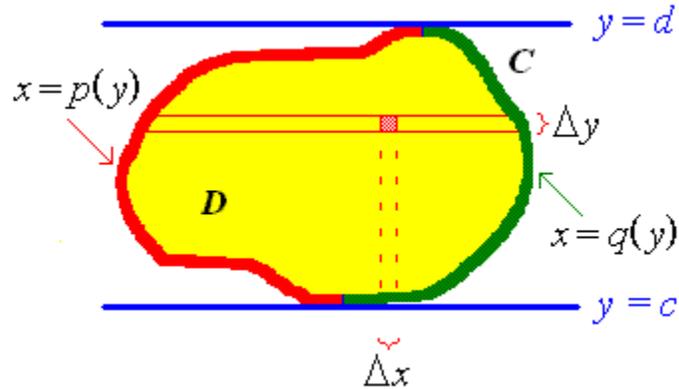
Consider a convex region  $D$  as shown. Left and right boundaries can be identified.

Then

$$\iint_D \frac{\partial Q}{\partial x} dA = \int_c^d \int_{p(y)}^{q(y)} \frac{\partial Q}{\partial x} dx dy$$

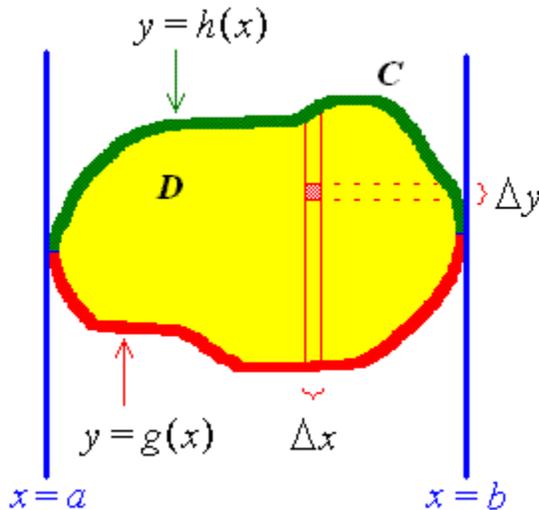
$$= \int_c^d \left[ Q(x, y) \right]_{x=p(y)}^{x=q(y)} dy$$

$$= \int_c^d (Q(q(y), y) - Q(p(y), y)) dy = \int_c^d Q(q(y), y) dy + \int_d^c Q(p(y), y) dy$$



But the path along  $x=q(y)$  from  $y=c$  to  $y=d$  followed by the path along  $x=p(y)$  from  $y=d$  back to  $y=c$  constitutes one complete circuit around the closed path  $C$ .

$$\Rightarrow \iint_D \frac{\partial Q}{\partial x} dA = \oint_C Q dy$$



Lower and upper boundaries for the region can also be identified.

$$\iint_D \frac{\partial P}{\partial y} dA = \int_a^b \int_{g(x)}^{h(x)} \frac{\partial P}{\partial y} dy dx$$

$$= \int_a^b \left[ P(x, y) \right]_{y=g(x)}^{y=h(x)} dx$$

$$= \int_a^b (P(x, h(x)) - P(x, g(x))) dx$$

$$= - \int_b^a P(x, h(x)) dx - \int_a^b P(x, g(x)) dx$$

But the path along  $y=g(x)$  from  $x=a$  to  $x=b$  followed by the path along  $y=h(x)$  from  $x=b$  back to  $x=a$  constitutes one complete circuit around the closed path  $C$ .

$$\Rightarrow \iint_D \frac{\partial P}{\partial y} dA = - \oint_C P dx \Rightarrow \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C (P dx + Q dy)$$

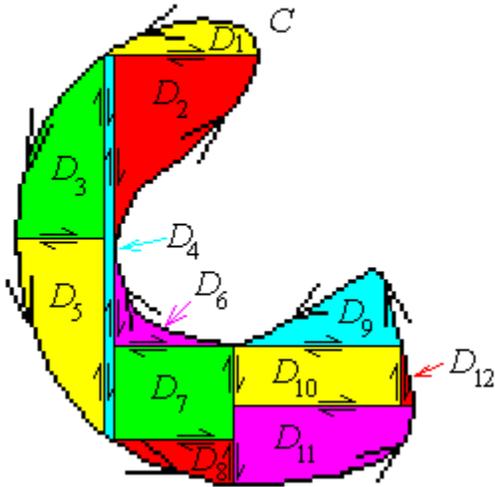
Green's Theorem (continued)

$$\text{But } \vec{F} \cdot d\vec{r} = \begin{bmatrix} P \\ Q \end{bmatrix} \cdot \begin{bmatrix} dx \\ dy \end{bmatrix} = P dx + Q dy$$

Therefore

$$\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C \vec{F} \cdot d\vec{r}$$

This proof can be extended to non-convex regions. Simply divide them up into convex sub-regions and apply Green's theorem to each sub-region.



The line integrals along common interior boundaries cancel out because they are travelled in opposite directions along the same line. The boundary of each convex sub-region  $D_i$  is a simple closed curve  $C_i$ , for which Green's theorem is valid:

$$\oint_{C_i} \vec{F} \cdot d\vec{r} = \iint_{D_i} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

$$\Rightarrow \sum_{\forall i} \oint_{C_i} \vec{F} \cdot d\vec{r} = \sum_{\forall i} \iint_{D_i} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

Therefore Green's theorem is also valid for any simply-connected region.

[Space for Additional Notes]

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