

# Behaviour Specification

A *reactive* system is a system that must react to external events:

- A Calculator must react to the keypresses.
- A Microwave oven must react to keypresses and also to the passage of time.
- An internet Router must react to the arrival of packets.
- A synchronous hardware circuit must react to the clock ticks.

Most systems can be viewed as reactive.

We can specify and/or model a reactive system using state machines.

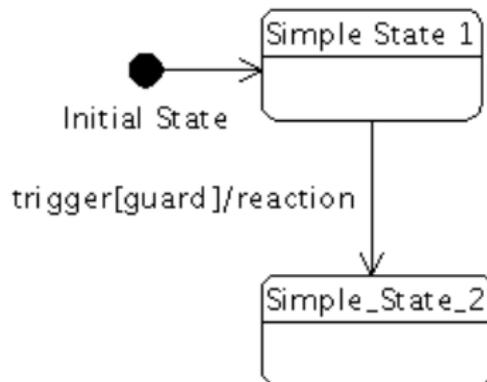
# StateCharts

*StateCharts* is a diagrammatic language for modelling finite state systems.

There are various flavours of StateCharts.

We'll use UML StateCharts.

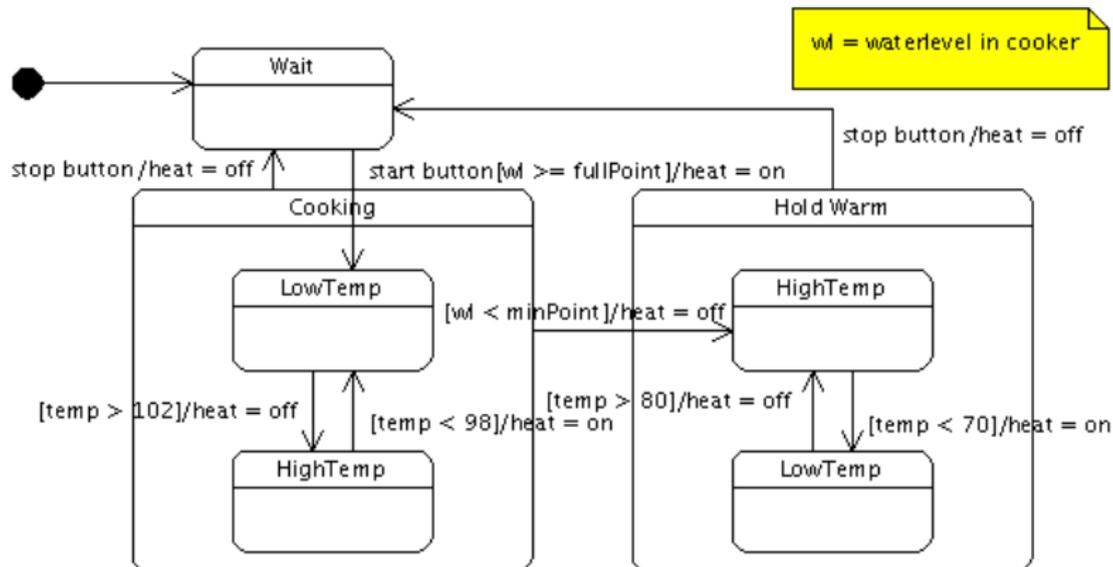
- *trigger* — the event that causes a transition.
- *guard* — a condition that must be true for the transition to occur.
- *reaction* — event or change of system variables at the instant of the transition.
- Time passes in states.
- Transitions are instantaneous.



## Statecharts (cont'd)

- All of trigger, guard and reaction are optional.
  - If trigger is omitted then transition occurs as soon as guard is true.
  - If guard is omitted then guard is *true*.
  - If reaction is omitted then there is no reaction, just state change.
- Triggers may be parameterized.
- Conditions can be used to
  - Inhibit transitions — if condition is false then transition can't occur.
  - Select between alternatives — universal & mutually exclusive guards (e.g., [ $x < \text{SetPoint}$ ], [ $x \geq \text{SetPoint}$ ]).
- Hierarchies of states can be formed:
  - non-orthogonal (“or”) states — whenever the super-state is active then exactly one of the sub-states is active.
  - orthogonal (“and”) states — concurrent state machines. Whenever the super-state is active one of the states in **each** of the sub-state(machine) is active.

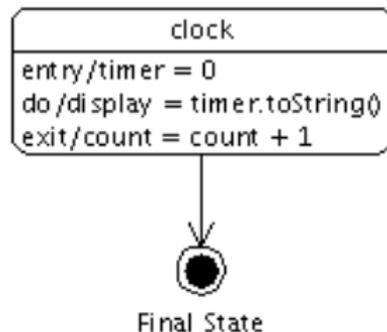
# Example: Rice Cooker



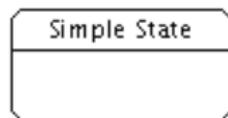
# Activities

States can be annotated with *activities*

- *entry* activities occur on entry to the state.
- *do* activities happen continuously when the state is active.
- *exit* activities occur on exit from the state.



# State Types



**Simple state** State with no substructure

**Initial state** A pseudostate that indicates the starting state when the enclosing state becomes active.



**Final state** A special state whose activation indicates the enclosing state has completed activity.

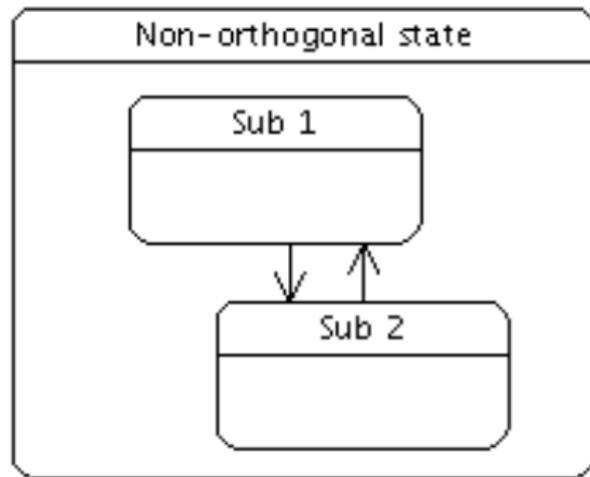



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<sup>0</sup>From [1].

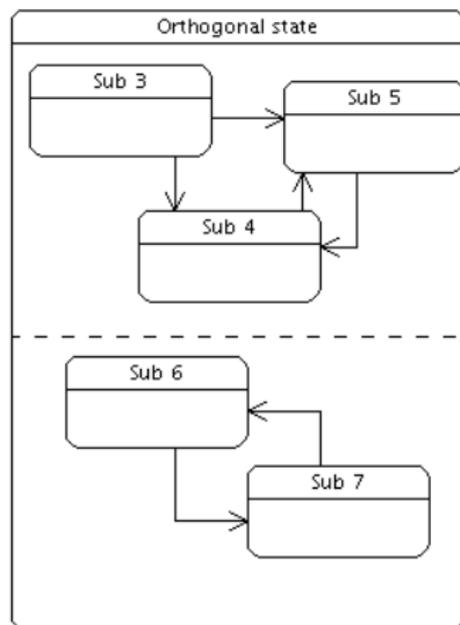
## State Types (cont'd): Non-orthogonal state

Composite state that contains one or more direct sub-states, exactly one of which is active at one time when the composite state is active.



## State Types (cont'd): Orthogonal state

Divided into two or more regions. One direct substate from each region is concurrently active when the composite state is active.



## State Types (cont'd): Orthogonal state

**Terminate** A special state whose activation terminates execution of the object owning the state machine.



**Junction** A pseudostate that chains transition segments into a single run-to-completion transition.



**Choice** A pseudostate that performs a dynamic branch within a single run-to-completion transition.

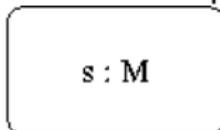


**History state** A pseudostate whose activation restores the previously active state within a composite state.

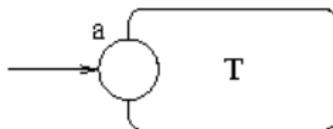


# State types (cont'd)

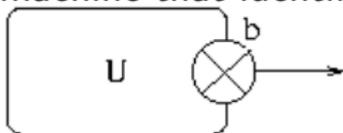
**Submachine state** State that references a state machine definition, which conceptually replaces the submachine state.



**Entry point** An externally visible pseudostate within a state machine that identifies an internal state as a target.



**Exit point** An externally visible pseudostate within a state machine that identifies an internal state as a source.



# Transitions

**External** Changes active state.

**Entry** Specifies an activity that occurs when a state becomes active.

**Exit** Specifies an activity that occurs when a state is exited.

**Internal** Causes execution of an effect but does not cause a change of state or execution of exit or entry activities. (Note: this is different from a self transition, which does invoke exit/entry activities.)

# References

- [1] James Rumbaugh, Ivar Jacobson, and Grady Booch.  
*The Unified Modeling Language Reference Manual*.  
Addison-Wesley, second edition, 2005.