

ENGINEERING 4020
MARINE FLUID DYNAMICS

QUIZ #2

Give a TRUE or FALSE answer to each of the following statements and briefly explain each answer: (1) lubrication flows are turbulent (2) boundary layers have a sharp outer edge (3) the circulation around a foil is caused by a doublet (4) a potential vortex is very viscous (5) head losses are governed by the Bernoulli Equation. [20] [BONUS: Identify formulas for each case on the formula sheets.]

State the conservation laws for fluid flows. Identify the integral forms of the laws on the formula sheets. Identify the stream tube forms of the laws on the formula sheets. Outline the derivation of each stream tube law. [20]

The general menu for the CFD software FLOW-3D is attached. Outline the function of each of the submenus at the top of this menu. Where appropriate use sketches to illustrate your answer. Explain briefly how FLOW-3D works. [20]

A certain pump moves cooling water through a closed pipe on a ship at 60 GPM. The overall length of the pipe is 25m. Its diameter is 5cm. It has sixty 180° bends and one globe valve. How would you get the demand curve for the system? How you would get the pump power? How would you determine the type of pump? What would NPSH tell you? [40]

wave - FLOW-3D - [General]

FileDiagnosticsPreferenceUtilitiesSimulateHelp

Navigator

Model Setup

Simulate

Analyze

Display

General

Physics

Fluids

Meshing Geometry

Boundaries

Initial

Output

Numerics

Finish time25.0

Restart

Interface tracking

☐ Free surface or sharp interface

☒ No sharp interface

Number of fluids

☒ One fluid

☐ Two fluids

Units

Simulation units

SI

Finish condition

☒ Finish time

☐ Fill fraction

☐ Solidified fluid fraction

Finish fraction1.0

Flow mode

☒ Incompressible

☐ Compressible

☐ Steady-state accelerator

(Non-physical transients)

Mentor options

☐ No mentor he

☐ Offer sugges

☒ Offer sugges

Version options

VersionDouble precision

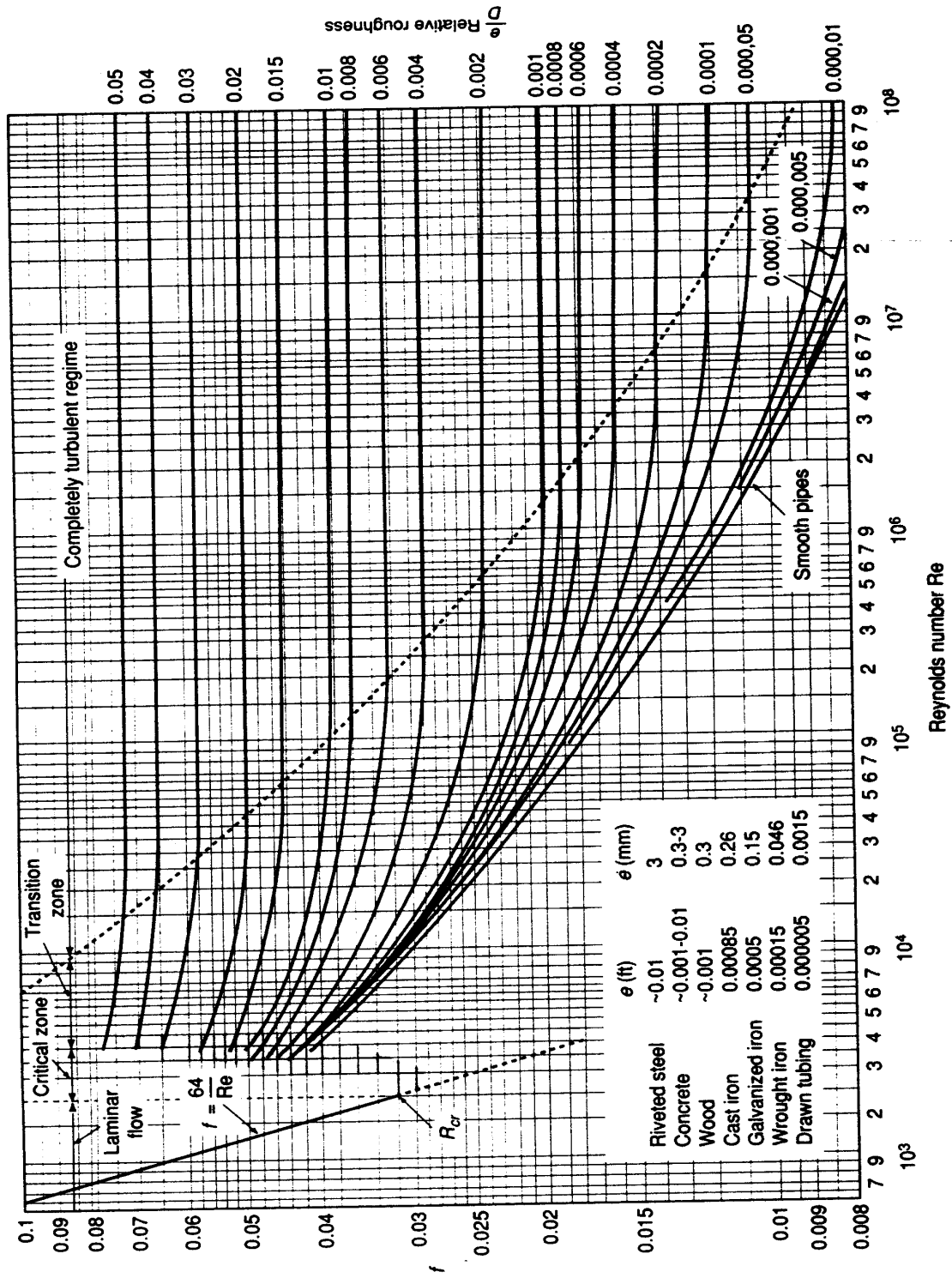
Number of processorsAll Available

☐ Run serial code if parallel tokens in use

Notes

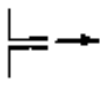
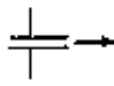
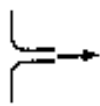
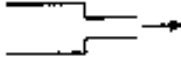
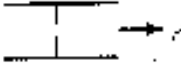
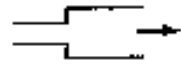


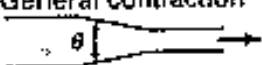
Font...

rotor in current



Moody diagram. (From L. F. Moody, *Trans. ASME*, Vol. 66, 1944.)

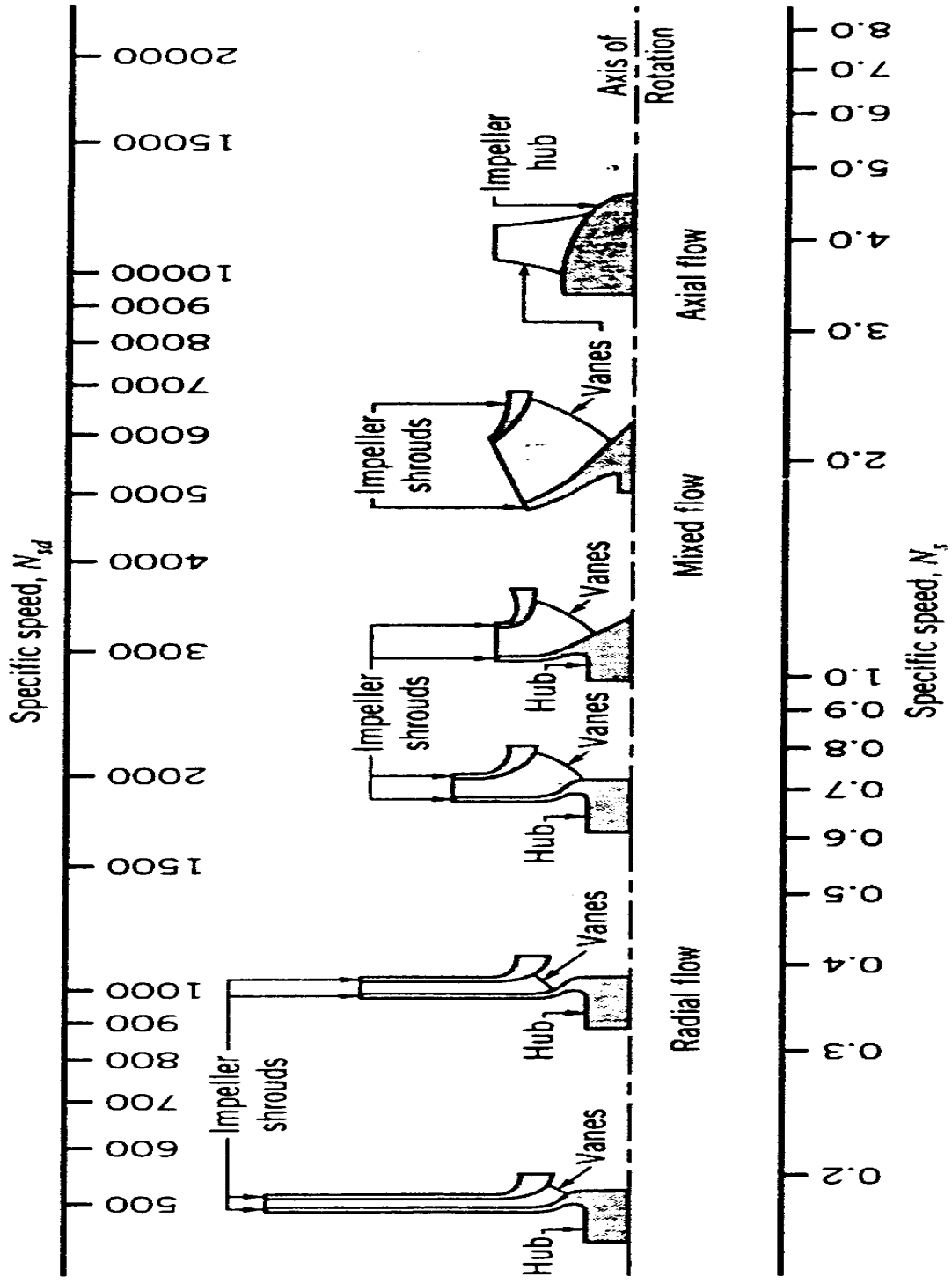
Nominal Loss Coefficients K (Turbulent Flow)^a

Type of fitting	Screwed			Flanged		
Diameter	1 in.	2 in.	4 in.	2 in.	4 in.	8 in.
Globe valve (fully open)	8.2	6.9	5.7	8.5	6.0	5.8
(half open)	20	17	14	21	15	14
(one-quarter open)	57	48	40	60	42	41
Angle valve (fully open)	4.7	2.0	1.0	2.4	2.0	2.0
Swing check valve (fully open)	2.9	2.1	2.0	2.0	2.0	2.0
Gate valve (fully open)	0.24	0.16	0.11	0.35	0.16	0.07
Return bend	1.5	.95	.64	0.35	0.30	0.25
Tee (branch)	1.8	1.4	1.1	0.80	0.64	0.58
Tee (line)	0.9	0.9	0.9	0.19	0.14	0.10
Standard elbow	1.5	0.95	0.64	0.39	0.30	0.26
Long sweep elbow	0.72	0.41	0.23	0.30	0.19	0.15
45° elbow	0.32	0.30	0.29			
Square-edged entrance			0.5			
Reentrant entrance			0.8			
Well-rounded entrance			0.03			
Pipe exit			1.0			
	Area ratio					
Sudden contraction ^b	2:1		0.25			
	5:1		0.41			
	10:1		0.46			
						
	Area ratio A/A_0					
Orifice plate	1.5:1		0.85			
	2:1		3.4			
	4:1		29			
	$\geq 6:1$		$2.78\left(\frac{A}{A_0} - 0.6\right)^2$			
						
Sudden enlargement ^c			$\left(1 - \frac{A_1}{A_2}\right)^2$			
90° miter bend (without vanes)			1.1			
(with vanes)			0.2			
General contraction	(30° included angle)		0.02			
	(70° included angle)		0.07			
						

^aValues for other geometries can be found in *Technical Paper 410*, The Crane Company, 1957.

^bBased on exit velocity V_2 .

^cBased on entrance velocity V_1 .



$$D/Dt \int_V \rho \, dV = \int_V \partial \rho / \partial t \, dV + \int_S \rho \, \mathbf{v} \cdot \mathbf{n} \, dS = 0$$

$$\begin{aligned} D/Dt \int_V \rho \mathbf{v} \, dV &= \int_V \partial \rho \mathbf{v} / \partial t \, dV + \int_S \rho \mathbf{v} \, \mathbf{v} \cdot \mathbf{n} \, dS \\ &= \int_S \boldsymbol{\sigma} \, dS + \int_V \rho \mathbf{b} \, dV \end{aligned}$$

$$\begin{aligned} D/Dt \int_V \rho e \, dV &= \int_V \partial \rho e / \partial t \, dV + \int_S \rho e \, \mathbf{v} \cdot \mathbf{n} \, dS \\ &= - \int_S \mathbf{q} \cdot \mathbf{n} \, dS + \int_S \mathbf{v} \cdot \boldsymbol{\sigma} \, dS \end{aligned}$$

$$\Sigma[\rho\mathbf{C}\mathbf{A}]_{\text{OUT}} - \Sigma[\rho\mathbf{C}\mathbf{A}]_{\text{IN}} = 0$$

$$\Sigma \dot{\mathbf{M}}_{\text{OUT}} - \Sigma \dot{\mathbf{M}}_{\text{IN}} = 0 \qquad \Sigma \dot{\mathbf{M}}_{\text{OUT}} = \Sigma \dot{\mathbf{M}}_{\text{IN}}$$

$$\begin{aligned} & \Sigma[\rho\mathbf{v}\mathbf{C}\mathbf{A}]_{\text{OUT}} - \Sigma[\rho\mathbf{v}\mathbf{C}\mathbf{A}]_{\text{IN}} \\ &= - \Sigma[\mathbf{P}\mathbf{A}\mathbf{n}]_{\text{OUT}} - \Sigma[\mathbf{P}\mathbf{A}\mathbf{n}]_{\text{IN}} + \mathbf{R} \end{aligned}$$

$$\Sigma [\dot{\mathbf{M}} \mathbf{U}]_{\text{OUT}} - \Sigma [\dot{\mathbf{M}} \mathbf{U}]_{\text{IN}} = - \Sigma \mathbf{P}\mathbf{A}\mathbf{n}_{\mathbf{x}} + \mathbf{R}_{\mathbf{x}}$$

$$\Sigma [\dot{\mathbf{M}} \mathbf{V}]_{\text{OUT}} - \Sigma [\dot{\mathbf{M}} \mathbf{V}]_{\text{IN}} = - \Sigma \mathbf{P}\mathbf{A}\mathbf{n}_{\mathbf{y}} + \mathbf{R}_{\mathbf{y}}$$

$$\Sigma [\dot{\mathbf{M}} \mathbf{W}]_{\text{OUT}} - \Sigma [\dot{\mathbf{M}} \mathbf{W}]_{\text{IN}} = - \Sigma \mathbf{P}\mathbf{A}\mathbf{n}_{\mathbf{z}} + \mathbf{R}_{\mathbf{z}}$$

$$\begin{aligned} & \Sigma [\dot{\mathbf{M}} (\mathbf{C}^2/2 + g\mathbf{z})]_{\text{OUT}} - \Sigma [\dot{\mathbf{M}} (\mathbf{C}^2/2 + g\mathbf{z})]_{\text{IN}} = \\ & - \Sigma[\mathbf{P}\mathbf{A}\mathbf{C}]_{\text{OUT}} + \Sigma[\mathbf{P}\mathbf{A}\mathbf{C}]_{\text{IN}} + \Sigma\dot{\mathbf{T}} - \Sigma\dot{\mathbf{L}} \end{aligned}$$

$$\Sigma [\dot{\mathbf{M}} g\mathbf{h}]_{\text{OUT}} - \Sigma [\dot{\mathbf{M}} g\mathbf{h}]_{\text{IN}} = + \Sigma\dot{\mathbf{T}} - \Sigma\dot{\mathbf{L}}$$

$$\mathbf{h} = \mathbf{C}^2/2g + \mathbf{P}/\rho g + \mathbf{z}$$

$$\dot{\mathbf{T}} = \dot{\mathbf{M}} g\mathbf{h}_{\text{T}} \qquad \dot{\mathbf{L}} = \dot{\mathbf{M}} g\mathbf{h}_{\text{L}}$$

$$\mathbf{h}_{\text{OUT}} - \mathbf{h}_{\text{IN}} = \mathbf{h}_{\text{T}} - \mathbf{h}_{\text{L}}$$

$$\mathbf{h}_{\text{L}} = (\mathbf{f}\mathbf{L}/\mathbf{D} + \Sigma\mathbf{K}) \mathbf{C}^2/2g$$

$$C^2/2g + P/\rho g + z = K$$

$$C^2/2 \quad + \quad P/\rho \quad + \quad gz \quad = \quad \kappa$$

$$H = X + Y\;Q^2 \qquad Q = C\;A$$

$$X = \Delta \; [P/\rho g + z]$$

$$Y = \left[fL/D + \Sigma K \right] / \left[2gA^2 \right]$$

$$\boldsymbol{N} \quad = \quad [N \; \sqrt{Q}] / [H^{3/4}]$$

$$NPSH = P_s/\rho g + C_s C_s/2g - P_v/\rho g$$

$$d \; = \; (P_o - P_v) / \rho g \; - \; h_L \; - \; NPSH$$

$$\boldsymbol{P} = \Delta \; [T \; \omega] = \Delta \; [\rho Q \; V_t \; R \; \omega]$$

$$\boldsymbol{P} = \rho g \; H \; Q$$

$$\partial U/\partial x\,+\,\partial V/\partial y\,+\,\partial W/\partial z\,=\,0$$

$$\partial P/\partial x\,=\,\mu\,\,\partial^2U/\partial z^2$$

$$\partial P/\partial y\,=\,\mu\,\,\partial^2V/\partial z^2$$

$$0\,\,=\,\mu\,\,\partial^2W/\partial z^2$$

$$\rho\,\Gamma S\qquad\qquad\Gamma=4\pi SR\,\,\mathrm{Sink}$$

$$\kappa\!=\!\Theta\!+\!\varepsilon\qquad\qquad\varepsilon\!=\!\tan^{-1}\left[m/\left(n\!+\!a\right)\right]$$

$$a\,=\,\sqrt{[R^2\!-\!m^2]}\,-\,n$$

$$\alpha\,=\,x\,+\,\left[x a^2/\left(x^2\!+\!y^2\right) \right]$$

$$\beta\,=\,y\,-\,\left[y a^2/\left(x^2\!+\!y^2\right) \right]$$

$$\delta^*\,\,\mathbf{U}\qquad\qquad\delta^*\,=\,\int\,\left(1\!-\!U/\mathbf{U}\right)\mathrm{d}y\qquad\qquad\delta^*\!=\!\mathrm{I}\delta$$

$$\rho\,\,\mathbf{U}^2\,\,\Theta\qquad\qquad\Theta\,=\,\int\,U/\mathbf{U}\left(1\!-\!U/\mathbf{U}\right)\mathrm{d}y\qquad\qquad\Theta\!=\!\mathrm{J}\delta$$

$$U/\mathbf{U}\,=\,\left(Y/\delta\right)^{1/n}\qquad\qquad\tau\,=\,C\,\,\rho\mathbf{U}^2/\left(\mathbf{U}\delta/\nu\right)^{1/k}$$

$$\mathbf{D}/b\,=\,\rho\,\,\mathbf{U}^2\Theta\qquad\qquad\tau\,=\,d\left[\mathbf{D}/b\right]/dx\,=\,\rho\mathbf{U}^2\,d\Theta/dx$$

$$\mathbf{D}\,=\,M\,\,bL\,\,R_{\mathrm{EL}}^{-1/m}\,\,\rho\mathbf{U}^2\qquad\qquad\mathbf{W}\,=\,C\,\,B\,\,\rho\mathbf{U}^2/2$$

$$\mathbf{P}\,=\,\left[\,\,\mathbf{D}\,+\,\mathbf{W}\,\right]\,\,\mathbf{U}$$