

EXPERIMENTAL METHODS

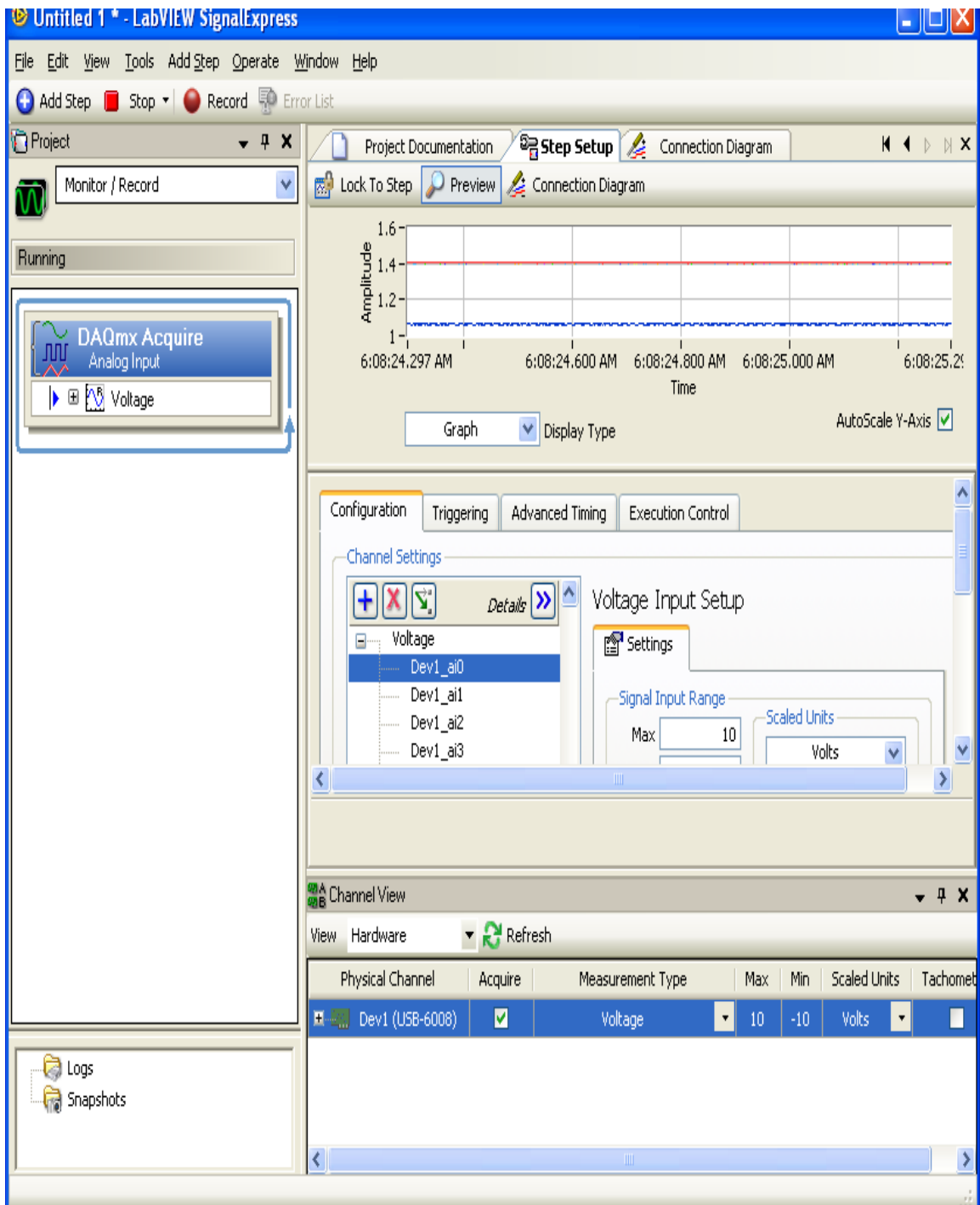
SIGNAL PROCESSING LAB

PURPOSE: The main purpose of this lab is to give you some experience doing spectral analysis of data using Fourier Transforms. Another purpose to give you some experience using LabView Signal Express.

SETUP: A boat free to pitch and heave has been installed in the wave tank. A boat pitch angle sensor and a capacitance wave probe have been wired to a NI DAQ. The DAQ reads data using LabView Signal Express. The wave board controller can make the board generate pure sinusoidal waves and random waves with a specific distribution of wave energy.

OBSERVATIONS: Measure the boat pitch response in both pure sinusoidal waves and random waves. Process the response and wave data using the Fast Fourier Transform code signals.m and the Standard Fourier Transform code waves.m. Apply a band pass filter to the data and repeat the data processing.





Untitled 1 - LabVIEW SignalExpress

File Edit View Tools Add Step Operate Window Help

Project Documentation Step Setup Connection Diagram

Click To Step Preview Connection Diagram

1.5
1.4
1.3

6:02:19.9

AutoScale Y-Axis ☒

Analysis

- Time-Domain Measurements
- Frequency-Domain Measurements
 - Octave Analysis
 - Sound Quality
 - Power Spectrum
 - Zoom Power Spectrum
 - Peak Search
 - Power in Band
 - Frequency Response
 - Tone Measurements
 - Distortion
 - Tone Extraction
 - Noise Measurements
- Order-Domain Measurements
- Test and Compare

Graph Display Type

Configuration Triggering Advanced Timing

Channel Settings

Voltage

- Dev1_ai0
- Dev1_ai1
- Dev1_ai2
- Dev1_ai3
- Dev1_ai4
- Dev1_ai5

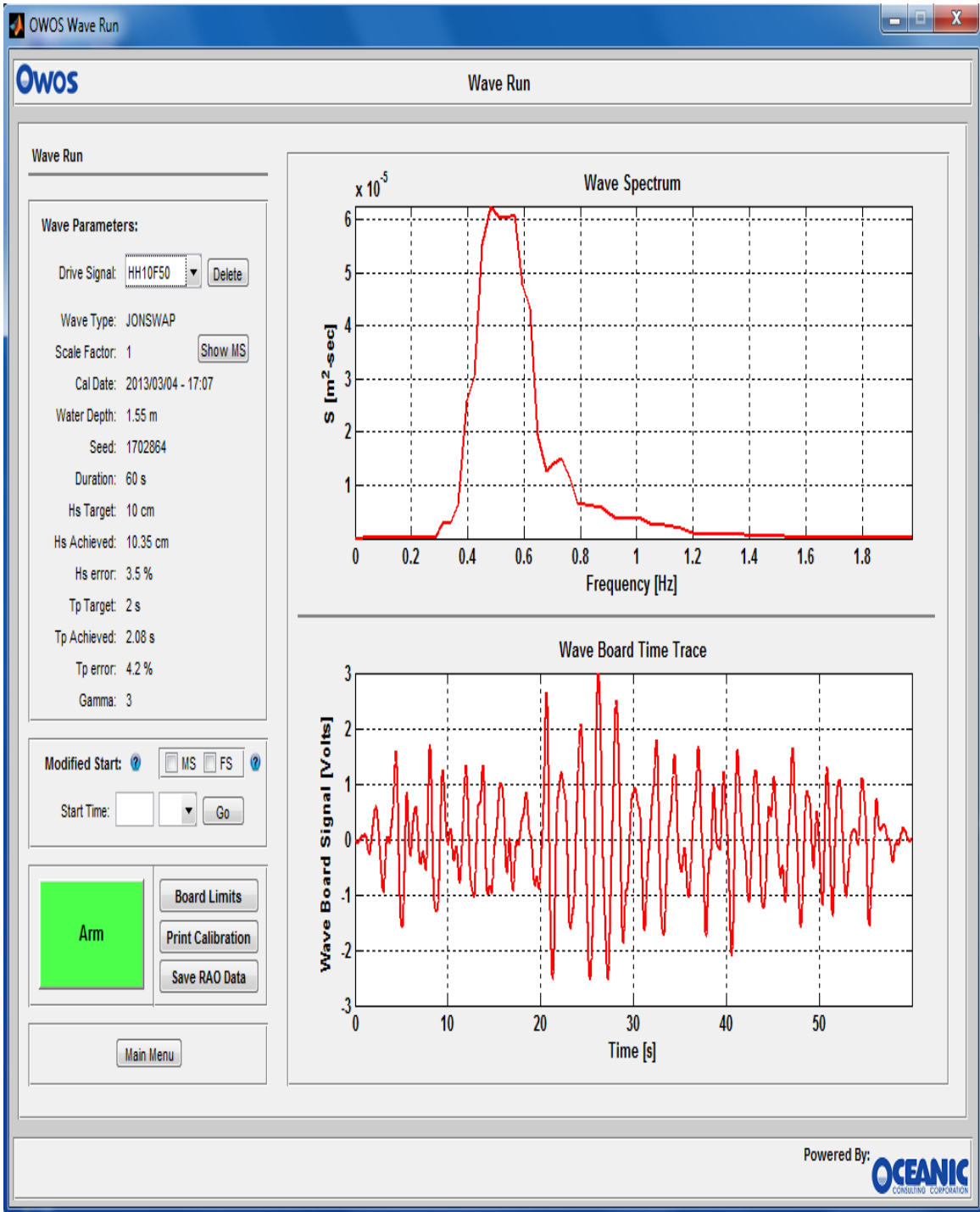
Min -10

Channel View

View Hardware Refresh

Physical Channel	Acquire	Measurement Type	Max	Min	Scaled Units	Tachomet
Dev1 (USB-6008)	☒	Voltage	10	-10	Volts	☐

Frequency-Domain Measurements



```

%
% BOAT PITCH IN RANDOM WAVES
%
% STANDARD FOURIER TRANSFORM
%
%
clear all
name='two.dat';
S=load(name);
nit=2250; mit=60;
delt=0.004; pad=150;
span=delt*nit;
period=0.1;
omega=2*pi/period;
for nat=1:nit
time=nat*delt;
t(nat)=time; window=1.0;
window=sin(pi*time/span);
shake(nat)=S(nat+pad,3)*window;
shake(nat)=sin(omega*time)*window;
end
shake=shake-mean(shake);
abc=0.0;
xyz=0.0;
omega=0.0;

```

```
for mat=1:mit
omega=omega+pi;
hz(mat)=omega/(2*pi);
time=0.0;
for nat=1:nit
time=time+delt;
one=sin(omega*time)*delt;
two=cos(omega*time)*delt;
abc=abc+shake(nat)*one;
xyz=xyz+shake(nat)*two;
end
sum=abc^2+xyz^2;
sum=(abc^2+xyz^2)^0.5;
level(mat)=2*sum/span;
abc=0.0; xyz=0.0;
end
figure(1)
plot(t,shake)
xlabel('time')
ylabel('data')
title('test')
figure(2)
plot(hz,level)
xlabel('hz')
ylabel('data')
title('spectrum')
```

```

%
% BOAT PITCH IN RANDOM WAVES
%
% FAST FOURIER TRANSFORM
%
%
clear all
name='one.dat';
S=load(name);
pad=50; out=250;
cycle=250.0; deltt=1/cycle;
nit=1024; mit=2*nit;
bit=nit+1; f(1)=0.0;
for it=1:nit
    iot=it+1;kit=it+pad;
    shake(it)=S(kit,3);
    f(iot)=cycle/2*iot/nit;
end
shake=shake-mean(shake);
z=fft(shake,mit)/nit;
p=2*abs(z(1:bit));
q=p.*conj(p);
plot(f(1:out),q(1:out))
xlabel('hz')
ylabel('g level')
title('spectrum')

```