

Object invariants

Conceptually an object is rather like a loop:

The lifetime behaviour of an object of class

class C

private var $f0 : T0$

private var $f1 : T1$

public constructor() U end constructor

public method $m0() S0$ end $m0$

public method $m1() S1$ end $m1$

end C

is described by this loop

var $f0 : T0$

var $f1 : T1$

U

while true do

var $m : \text{message} := \text{get next message}$

switch(m)

case $m0$ do $S0$ end case

case $m1$ do $S1$ end case

end switch

end while

This loop may have a loop invariant.

Such an invariant reflects the “consistent” states of the object. I.e. the ones that “make sense”.

This loop invariant expresses what we expect to be true before and after each message.

We call such an invariant an **object invariant** or a **class invariant**.

It is implicitly a postcondition of construction and a pre- and postcondition of each method. I.e. each method must **preserve** the object invariant

Example

A date class

```
class GregorianCalendar
```

```
  private var  $d$  : int,  $m$  : int,  $y$  : int
```

```
  invariant  $y \geq 1 \wedge 1 \leq m \leq 12 \wedge 1 \leq d \leq 31$ 
```

```
  invariant  $m \in \{4, 6, 9, 11\} \Rightarrow d \leq 30$ 
```

```
  invariant  $m = 2 \Rightarrow d \leq 29$ 
```

```
  invariant  $m = 2 \wedge y \nmid 400 \wedge (y \nmid 4 \vee y \mid 100) \Rightarrow d \leq 28$ 
```

```
  ...
```

```
  public method incr()
```

```
     $d := d + 1$ 
```

```
    if  $d = 32$ 
```

```
       $\vee m \in \{4, 6, 9, 11\} \wedge d = 31$ 
```

```
       $\vee m = 2 \wedge d = 30$ 
```

```
       $\vee m = 2 \wedge y \nmid 400 \wedge (y \nmid 4 \vee y \mid 100) \wedge d = 29$ 
```

```
    then  $d := 1$   $m := m + 1$ 
```

```
      if  $m = 13$  then  $y := y + 1$   $m := 1$  end if end if
```

```
  end incr
```

```
end Date
```

Example

```

class DynamicArray⟨T⟩
  private var a : array⟨T⟩ := new array⟨T⟩(1)
  private var len: int := 0
  invariant  $0 \leq len \leq a.length$ 
  public method getLength( ) : int
    return len
  end getLength
  public method get( i : int ) : T
    precondition  $0 \leq i < getLength()$ 
    return a(i)
  end get
  public method set( i : int, v : T )
    precondition  $0 \leq i \leq getLength()$ 
    ...
  end set
  public method clipTo( i : int )
    precondition  $0 \leq len \leq a.length$ 
    changes a, len
    len := i
  end clipTo
end DynamicArray

```

In order for *get* to work we need that $0 \leq len \leq a.length$. Thus this is an invariant.

We need to ensure the invariant is true after object construction and after execution of each public method.

In return we can assume that it is true at the start of each public method.

Now let's look at implementing `DynamicArray` so as to preserve the invariant.

```

class DynamicArray⟨T⟩
  private var a : array⟨T⟩ := new array⟨T⟩(1)
  private var len: int := 0
  invariant  $0 \leq len \leq a.length \wedge 0 < a.length$ 
  ...
  public method set( i : int, v : T )
    precondition  $0 \leq i \leq getLength()$ 
    if  $i = len$  then
      len := len + 1
      if  $len > a.length$  then
        // Must restore the object invariant
        var b := new array ⟨T⟩ (a.length × 2)
        for  $j \leftarrow \{0, ..a.length\}$  do  $b(j) := a(j)$ 
        end for
        a := b
      end if
    end if
    a(i) := v
  end set
end DynamicArray

```

As with a loop invariant, the object invariant may be temporarily violated, but should be restored by the end of the routine.

For `set` to work, we need that the array has a positive length. This is why $0 < a.length$ is in the invariant. (Having changed the invariant, we must now check that all methods preserve it.)

Concrete data type

For a client programmer to know what the methods “mean”, they must read the implementation! This is not good.

For the implementing programmer, how can they know that they have implemented the methods correctly?

Can we describe the “meaning” of each method by pre- and postconditions? This will serve as a *contract* between the client and the implementer.

Let’s try.

[Notational notes:

- In postconditions, we will use v_0 to represent the value of a variable v at the start of a subroutine invocation.
- In postconditions, we use *result* to stand for the result.
- Variables not mentioned after “changes” do not change.]

```

class DynamicArray⟨T⟩
  private var a : array⟨T⟩ := new array⟨T⟩(1)
  private var len: int := 0
  invariant  $0 \leq len \leq a.length \wedge 0 < a.length$ 
  public method getLength( ) : int
    postcondition result = len
    return len
  end getLength
  public method get( i : int ) : T
    precondition  $0 \leq i < getLength()$ 
    postcondition result = a(i)
    return a(i)
  end get
  public method set( i : int, v : T )
    precondition  $0 \leq i \leq getLength()$ 
    changes a, len
    postcondition  $len = \max(i + 1, len_0) \wedge a(i) = v$ 
       $\wedge (\forall j : \{0, ..len_0\} \cdot j \neq i \Rightarrow a(j) = a_0(j))$ 
    ... as before ...
  end set
  public method clipTo( i : int )
    precondition  $0 \leq i \leq length(s)$ 
    changes a, len
    postcondition  $len = i \wedge (\forall j : \{0, ..i\} \cdot a(j) = a_0(j))$ 
      len := i
  end clipTo
end DynamicArray

```

But these contracts:

- are in terms of private variables that are really none of the client's business.
- are tied to the particular data representation that we chose to use.
- must change if that representation changes.
- (therefore, client code may become incorrect!)
- force reasoning about the client code to involve reasoning about the array-based implementation.

In short, they *violate information hiding*.

They don't really describe how a `DynamicArray` can be useful to a client in a way that abstracts away from the implementation particulars and leaves only the logical essence of the `DynamicArray`.

Let's start again.

Abstract data type

This time we will ignore implementation in terms of arrays and simply make use of a “sequence” type.

Notations for sequences

- $\text{Seq } \langle T \rangle$ — the type of all finite sequences with items of type T
- $[]$ — a sequence of length 0
- $[a]$ — a sequence of length 1
- $s \hat{ } t$ — the catenation of two sequences
- $s(i)$ — item i (starting at 0, of course)
- $s[i, ..j]$ — a segment from position i up to, but not including j
- $\text{length}(s)$ — the length of s

(Abstract data type for dynamic array.)

```

interface DynamicArrayI⟨T⟩
  ghost public readonly var s : Seq ⟨T⟩ := []
  public method getLength( ) : int
    postcondition result = length(s)
  public method get( i : int ) : T
    precondition  $0 \leq i < \text{length}(s)$ 
    postcondition result = s(i)
  public method set( i : int, v : T )
    precondition  $0 \leq i \leq \text{length}(s)$ 
    changes s
    postcondition  $s = s_0[0, ..i] \wedge [v] \wedge s_0[i + 1, ..\text{length}(s)]$ 
  public method clipTo( i : int )
    precondition  $0 \leq i \leq \text{length}(s)$ 
    changes s
    postcondition  $s = s_0[0, ..i]$ 
end DynamicArrayI

```

This version precisely documents the **interface** of an abstract data type.

We call *s* an **abstract** field or a **ghost** field

But what about the implementation?

We data refine the class.

Introduce (**concrete**) fields *len* and *a* to represent *s*.

The linking invariant is

$$\begin{aligned}
 LI : & \text{length}(s) = \text{len} \leq a.\text{length} \\
 & \wedge a.\text{length} > 0 \\
 & \wedge (\forall j : \{0, ..\text{len}\} \cdot s(j) = a(j))
 \end{aligned}$$

Once we have decided on the linking invariant, the individual methods can be implemented independently of each other.

The complete class is this

```

class DynamicArray $\langle T \rangle$  implements DynamicArrayI $\langle T \rangle$ 
  // ghost variable  $s : \text{Seq } \langle T \rangle := []$  is inherited
  private var  $a : \text{array } \langle T \rangle := \text{new array } \langle T \rangle(1)$ 
  private var  $len : \text{int} := 0$ 
  invariant  $length(s) = len \leq a.length \wedge a.length > 0$ 
     $\wedge (\forall j : \{0, ..len\} \cdot s(j) = a(j))$ 
  public method getLength( ) : int
    postcondition  $result = length(s)$ 
    return  $len$ 
  end getLength
  public method get(  $i : \text{int}$  ) :  $T$ 
    precondition  $0 \leq i < length(s)$ 
    postcondition  $result = s(i)$ 
    return  $a(i)$ 
  end get
  public method set(  $i : \text{int}, v : T$  )
    precondition  $0 \leq i \leq length(s)$ 
    changes  $s$ 
    postcondition  $s = s_0[0, ..i] \wedge [v] \wedge s_0[i + 1, ..length(s)]$ 
    ...as before...
    ghost  $s := s[0, ..i] \wedge [v] \wedge s[i + 1, ..length(s)]$ 
  end set

```

```

public method clipTo( i : int )
  precondition  $0 \leq i \leq \text{length}(s)$ 
  changes s
  postcondition  $s = s_0[0, ..i]$ 
  len := i
  ghost s := s[0, ..i]
end DynamicArray

```

The annotation "ghost" indicates code that is only needed for verification — it should not be compiled.

When is a subroutine correct? Consider *clipTo*. We should show

$$\begin{aligned}
& \{0 \leq i \leq \text{length}(s) \wedge s_0 = s \wedge LI\} \\
& \textit{len} := i \quad s := s[0, ..i] \\
& \{s = s_0[0, ..i] \wedge LI\}
\end{aligned}$$

The object invariant that we had earlier

$$\textit{len} \leq a.\text{length} \wedge 0 < a.\text{length}$$

is merely the part of the linking invariant that involves only the concrete variables

We call this the **concrete invariant**.

(Technically the concrete invariant can be obtained from the linking invariant, by “projecting” onto the concrete space $CI = (\exists s \cdot LI)$.)

This concrete invariant can (and likely should) be checked using run-time assertion checking. (Unless 0-false-negative static verification technology is used, in which case, run-time checking would be superfluous.)

There is also an abstract invariant. In this example it is true, as we put no restrictions on the sequence being represented.

(Technically the abstract invariant can be obtained from the linking invariant, by “projecting” onto the abstract space $AI = (\exists len \cdot \exists a \cdot LI)$.)

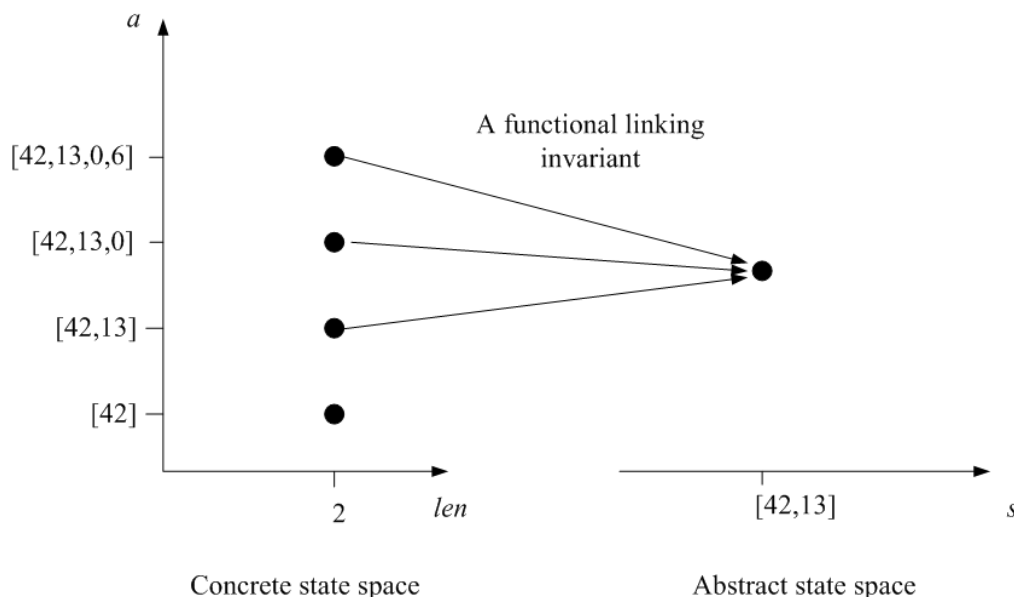
You can think of the ghost variables as being the axes of a state space. We call this the **abstract state space** of the ADT.

In the dynamic array example there is only one axis s of the abstract state space

The concrete variables are the axes of a **concrete state space**.

In the dynamic array example, the axes of the concrete state space are a and len .

The linking invariant links points in the concrete state space with points in the abstract state space.



For example $s = [42, 13]$ is a point in the abstract state space.

It is linked to every concrete point such that $len = 2 \leq a.length \wedge a(0) = 42 \wedge a(1) = 13$.

In this example:

- * Every point in the abstract space is linked to an infinity

of points in the concrete space.

- * Every point in the concrete space, which obeys the concrete invariant, is linked to exactly one point in the abstract space.