

PThreads

In C & C++, one of the most common libraries for concurrency is called **POSIX Threads** (Or **PThreads**.)

This provided signal and continue style monitors.

Bounded buffer using PThreads

Data Structure

A “mutex” object plays the role of the monitor.

A “condition” objects provide condition queues.

```
class BoundedBuffer {  
    private: static int const N = 10 ;  
    private: int buf[N] ;  
    private: int front, length ;  
    private: pthread_mutex_t entryMutex ;  
    private: pthread_cond_t bufferNotEmpty ;  
    private: pthread_cond_t bufferNotFull ;
```

Initialization

Mutex and condition objects must be initialized.

I did this in my constructor.

```
public: BoundedBuffer() {  
    pthread_mutex_init( &entryMutex, NULL ) ;  
    pthread_cond_init( &bufferNotEmpty, NULL ) ;  
    pthread_cond_init( &bufferNotFull, NULL ) ;
```

```
front = 0 ;
length = 0 ; }
```

Destruction

```
public: ~BoundedBuffer() {
    pthread_mutex_destroy( &entryMutex ) ;
    pthread_cond_destroy( &bufferNotEmpty ) ;
    pthread_cond_destroy( &bufferNotFull ) ; }
```

Mutual exclusion

Each entry point must explicitly lock and unlock the monitor

```
public: void put( int value ) {
    pthread_mutex_lock( &entryMutex ) ;
    ...
    pthread_mutex_unlock( &entryMutex ) ; }
```

Waiting and signalling

```
public: void put( int value ) {
    pthread_mutex_lock( &entryMutex ) ;
    while( length == N )
        pthread_cond_wait(
            &bufferNotFull,
            &entryMutex ) ;
    assert( length < N ) ; }
```

```
    buf[ (front + length) % N ] = value ;  
    ++length ;  
    pthread_cond_broadcast( &bufferNotEmpty )  
    ;  
    pthread_mutex_unlock( &entryMutex ) ; }
```

- Because of signal and continue semantics the wait must happen in a loop.
- Note that the “wait” routine mentions the mutex, this is because conditions objects are not explicitly associated with mutex objects.
- The “broadcast” subroutine is a “signalAll”, all waiting threads are awakened.

Threads in PThreads

PThreads also provides facilities for creating threads that share shared memory.

Depending on the implementation, threads may be

- Native threads — known to and scheduled by the OS
- User level threads — not known to the OS. The user process must arrange for switching the CPU between threads.
- Nonpreemptive threads — GNU Portable Threads supports cooperative multitasking. There is no actual concurrency.

Only native threads allow you to take advantage of multiple cores.